LARGE AREA, REAL TIME INSPECTION OF ROCKET MOTORS USING A NOVEL HANDHELD ULTRASOUND CAMERA





J. W. Gurney, M. E. Lasser, R. S. Lasser, J. P. Kula, D. C. Rich Imperium, Inc.
Silver Spring, MD
B. J. VanderHeiden
Alliant Techsystems, Inc.
Magna, UT

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Report Documentation Page

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Purpose of Work

- Describe operation of Imperium ultrasound camera
- Describe work done with camera under Air Force Research Laboratory SBIR program
- Present results to date and work remaining under this contract

Objectives

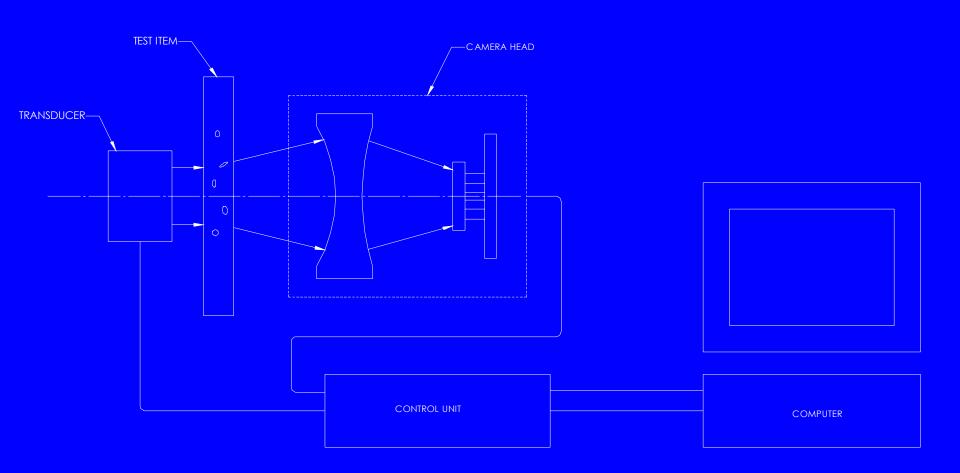
Phase I

 Demonstrate the applicability of the Imperium ultrasound camera to the inspection of Solid Rocket Motors (SRM)

Phase II

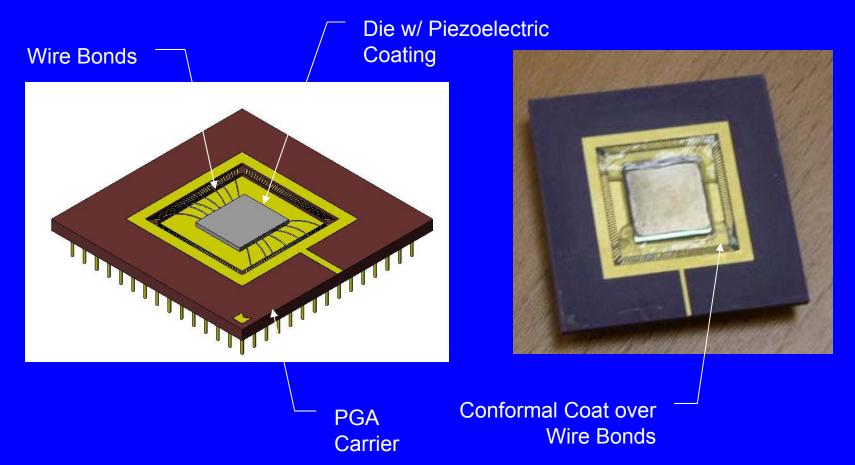
- Develop a prototype camera that can be used in either handheld or production settings
- Test prototype camera to determine:
 - Level of performance
 - Ability to detect typical flaws
 - Determine potential time savings

System Configuration

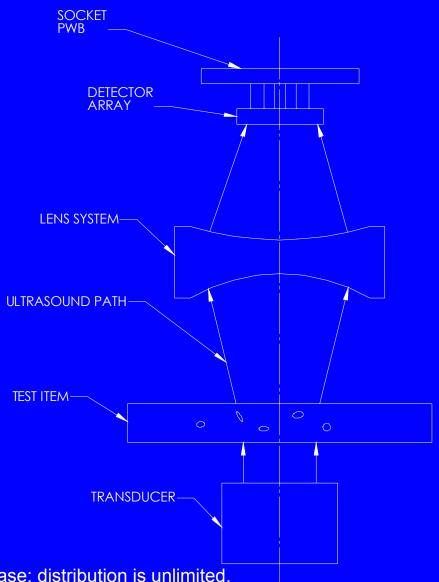


Detector Array

- Key feature to creating ultrasound camera
- Converts ultrasound to electrical signal



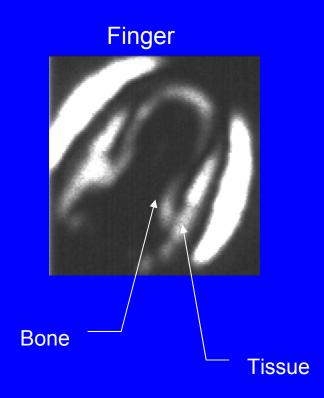
Operation – Thru-Transmission



Operation – Pulse Echo

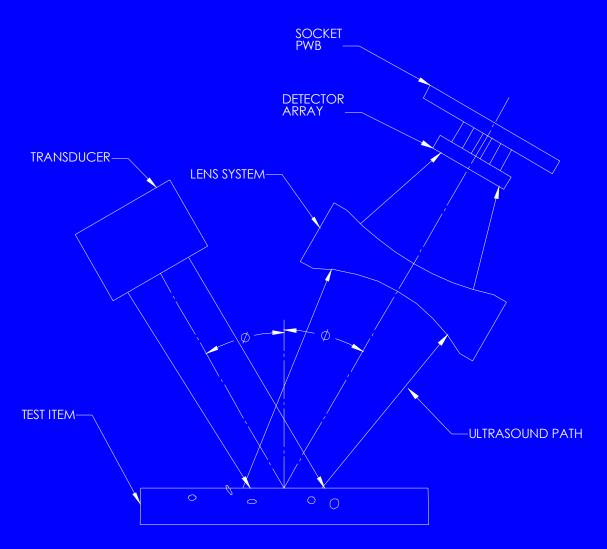
Often done in water tank:





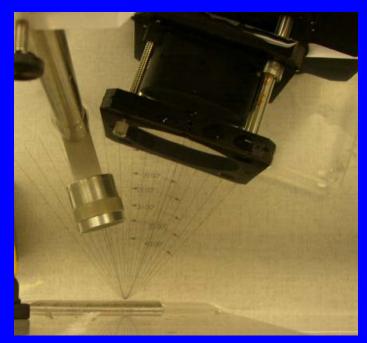
Dark areas have high attenuation

Operation – Pitch-Catch



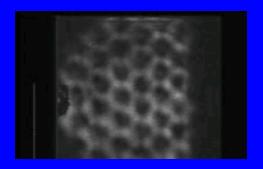
Operation – Pitch-Catch (cont.)

 Often done in water tank, but portable cameras are feasible

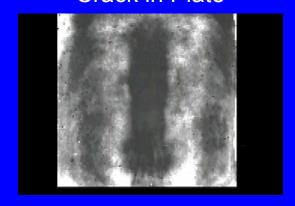


 White areas where there is the highest reflection

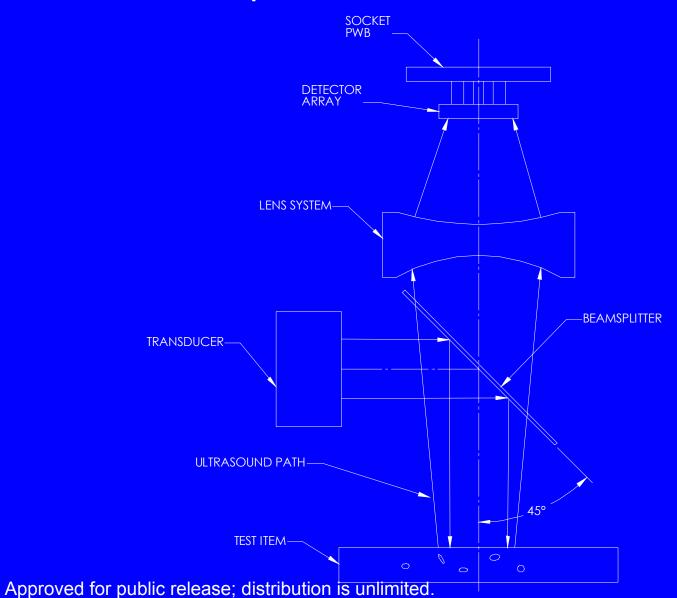
Hole in Core



Crack in Plate



Operation – Pulse-Echo



Operation – Pulse-Echo (cont.)

- Beamsplitter allows for collinear transducer beam
- 50% of pressure is lost in reflections

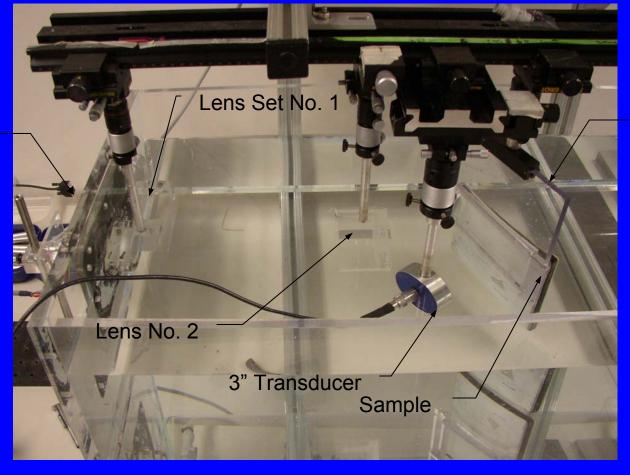


- White areas are regions of high reflectivity
- Range gating is feasible

Phase I Effort

Demonstrated feasibility when tested in Pitch-Catch mode

Camera



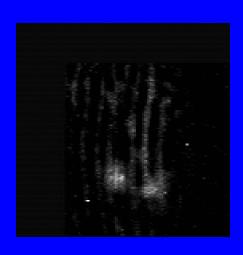
Fixture for Positioning Sample

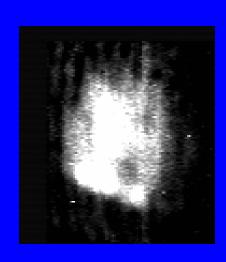
Phase I Effort (cont.)

Demonstrated ability to detect flaws in many sample parts

Undamaged

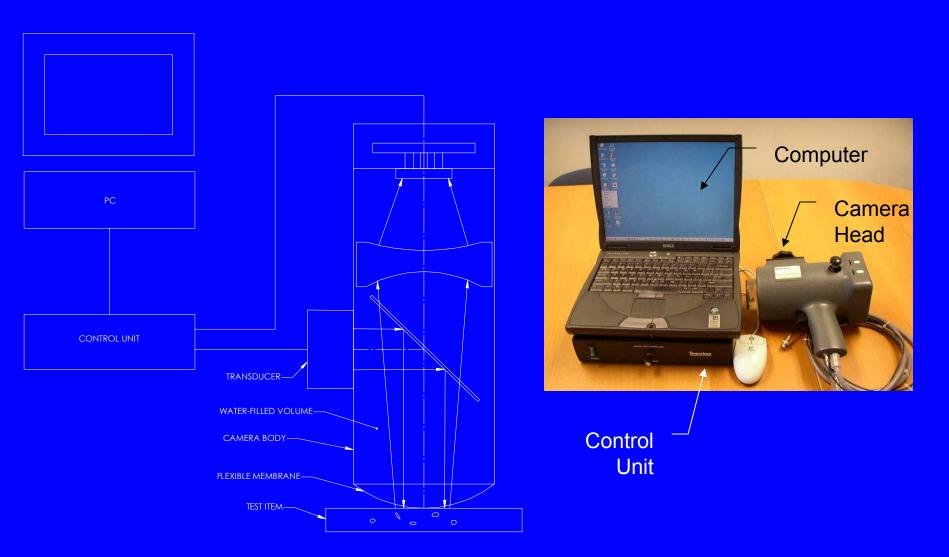
Delamination



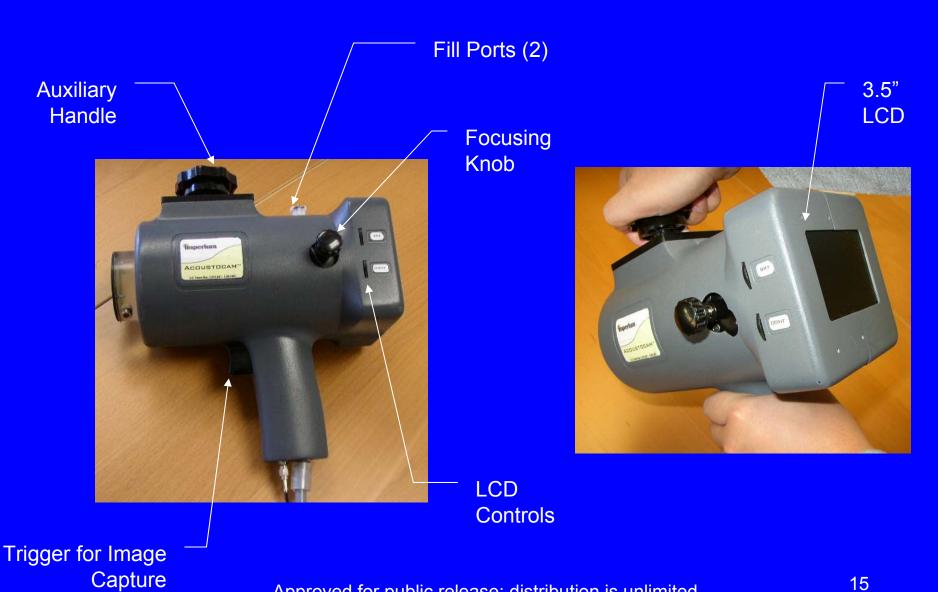


- 1 MHz transducer effective for many solid composites
- Up to 5 MHz used for some honeycomb core
- Exterior cork heat shield not successfully penetrated
- Phase II initiated

Phase II System Configuration



Camera Head



Portable System Performance

Demonstrated functional capability:



Production Camera

Designed to interface with existing SRM scanner





- ATK to compare scan times to existing production systems
- Working to create large composite image from multiple small images

Summary and Conclusions

- Concept demonstrated: capability of seeing flaws on representative composite parts
- Limited testing with portable system has detected similar flaws
- It is expected that production system will demonstrate a significant reduction in test time over present systems
- Concept is transferable to areas other than nondestructive evaluation of solid rocket motors

Future Work

Program Tasks

- Complete quantitative testing of system using calibrated standards
- Deliver system to ATK for in-plant use in both handheld and production configurations
- Submit test report on findings
- Deliver hardware to AFRL

IR&D

- Improve image quality
- High-speed digital downloads
- Increased FOV
- Decreased size and weight
- Improved range-gating